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The robot simulator CoppeliaSim, with integrated development environment, is based on a distributed control architecture: each object/model can be individually controlled via an embedded script, a plugin, a ROS or BlueZero node, a remote API client, or a custom solution. This makes CoppeliaSim very versatile and ideal for multi-robot applications. Controllers can be written in C/C++, Python, Java, Lua, Matlab or Octave.

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PyRep PyRep is a toolkit for robot learning research, built on top of CoppeliaSim (previously called V-REP). NOTE: V-REP has recently been changed to CoppeliaSim.

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